

# **Iris Liveness Detection by Relative Distance Comparisons**

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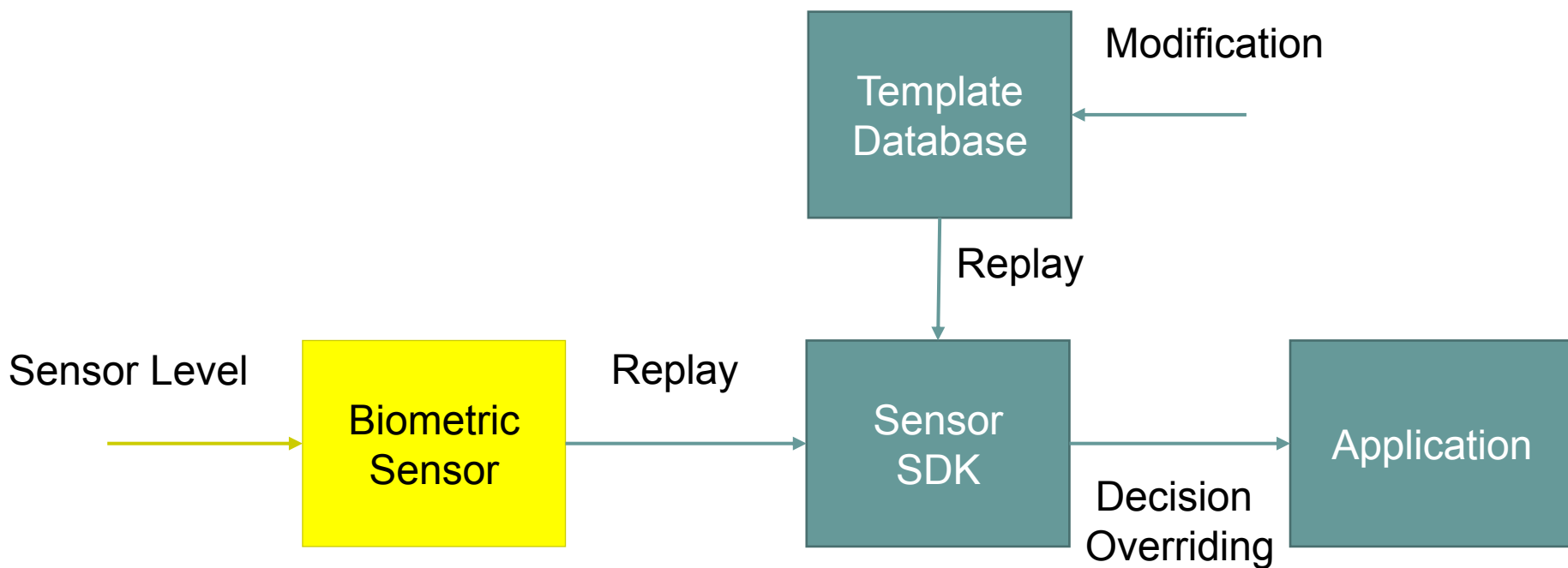
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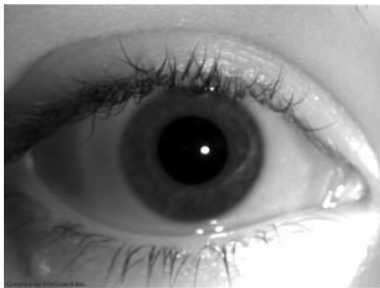
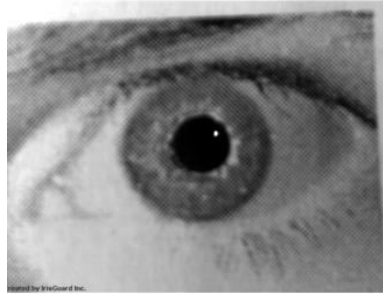
# Liveness Detection

- › Detect vitality from biometrics signature
- › Targeted to **sensor level** attacks



# Iris Liveness Detection

- ▶ Training
  - ▶ Collection of real and fake iris images
  - ▶ Photo attacks:



Adam Czajka - **Database of Iris Printouts and its Application: Development of Liveness Detection Method for Iris Recognition**, In: International Conference on Methods & Models in Automation & Robotics (2013)

# Iris Liveness Detection

- ▶ Training
  - ▶ Collection of real and fake images
  - ▶ Contact lens attacks:



real

fake (textured lens)

Contact lens

Daksha Yadav, Naman Kohli, James S. Doyle, Kevin Bowyer - **Unraveling the Effect of Textured Contact Lenses on Iris Recognition**, In: IEEE Transactions on Information Forensics and Security (2014)

# Artificial Intelligence Approach

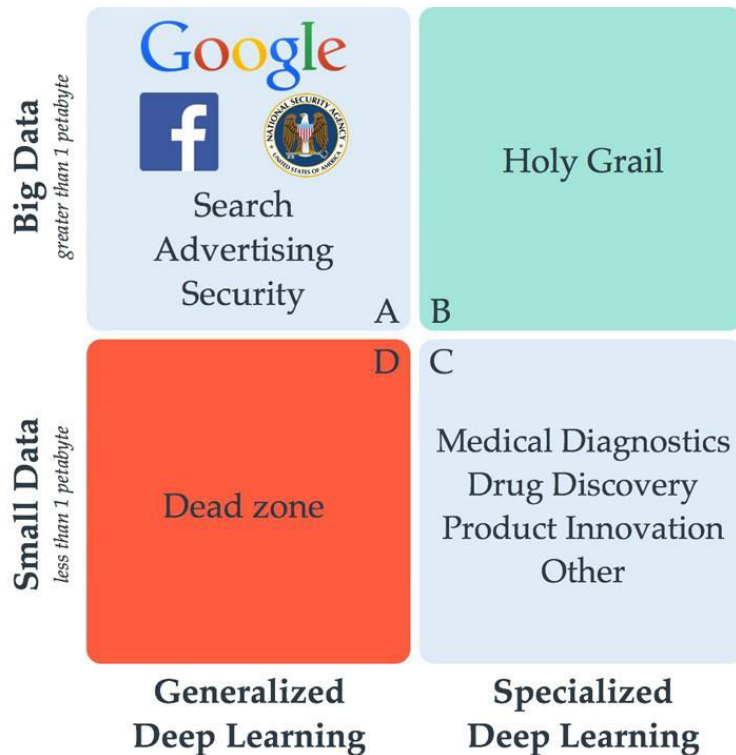
- › Let an intelligent agent perceive what are the characteristics that make a biometrics real or fake
- › Pattern recognition



- › Deep learning



# Specialized Deep Learning



benchmark	filter			SOTA
	random	optimized		
Warsaw	99.84	<i>cf10-11</i>	<i>spoofnets</i>	97.50
Biosec	98.93	59.08	47.67	100.00
MobBIOfake	98.63	99.13	100.00	99.75

David Menotti et Al. - **Deep Representations for Iris, Face, and Fingerprint Spoofing Detection**, In: IEEE Transactions on Information Forensics and Security (2015)

Shalini Ananda - **An Open Letter to Yann LeCun—Small Data Requires Specialized Deep Learning**, <https://tinyurl.com/smalldata>

# Our Approach

- ▶ Learn by comparing **local features**
  - ▶ Set of n reference real and fake patches:
    - ▶  $R_L = \{r(x_{L_1}), r(x_{L_2}), \dots, r(x_{L_n})\}$
    - ▶  $R_F = \{r(x_{F_1}), r(x_{F_2}), \dots, r(x_{F_n})\}$
  
- ▶ Matching problem:
  - ▶ Given a query image
    - ▶ Extract p patches  $Q = \{r(Q_1), r(Q_2), \dots, r(Q_p)\}$
  - ▶ Real if  $\sum_{j=1}^p D(R_L, Q_j) \geq \sum_{j=1}^p D(R_F, Q_j)$
  - ▶ Fake otherwise

# Architecture

Layer description	output
32x32 gray level image	
5x5 conv. filters, stride 1, 1 → 64 feat. maps	64x28x28
batch normalization	64x28x28
rectifier linear unit	64x28x28
3x3 conv. filters, stride 2, padding 1, 64 → 64 feat. maps	64x14x14
3x3 conv. filters, stride 1, 64 → 128 feat. maps	64x12x12
batch normalization	64x12x12
rectifier linear unit	64x12x12
3x3 conv. filters, stride 2, padding 1, 128 → 128 feat. maps	128x6x6
3x3 conv. filters, stride 1, 128 → 256 feat. maps	256x4x4
batch normalization	256x4x4
rectifier linear unit	256x4x4
3x3 conv. filters, stride 2, padding 1, 256 → 256 feat. maps	256x2x2
fully connected layer 4x256 → 256	256
dropout $p = 0.4$	256
rectifier linear unit	256
fully connected layer 256 → 256	256
softmax	256

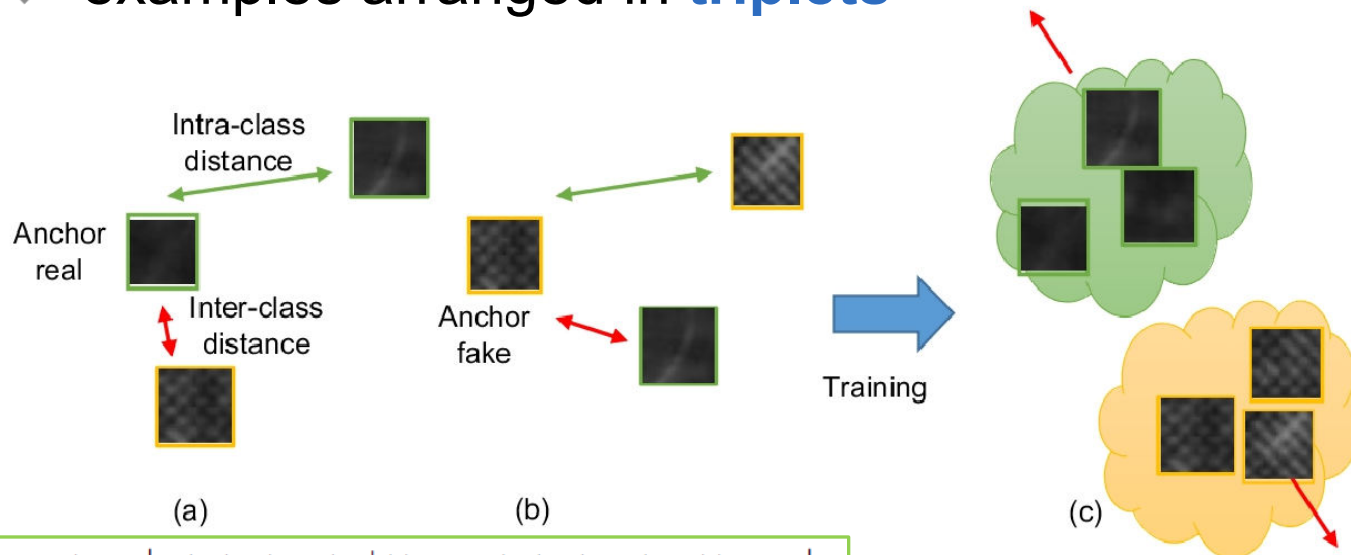
Jost Tobias Springenberg et Al. - **Striving for Simplicity: The All Convolutional Net**,  
In: ICLR workshop track (2015)



# Metric Learning

## › Increase **number of examples**

- › **patch** based representation
- › examples arranged in **triplets**

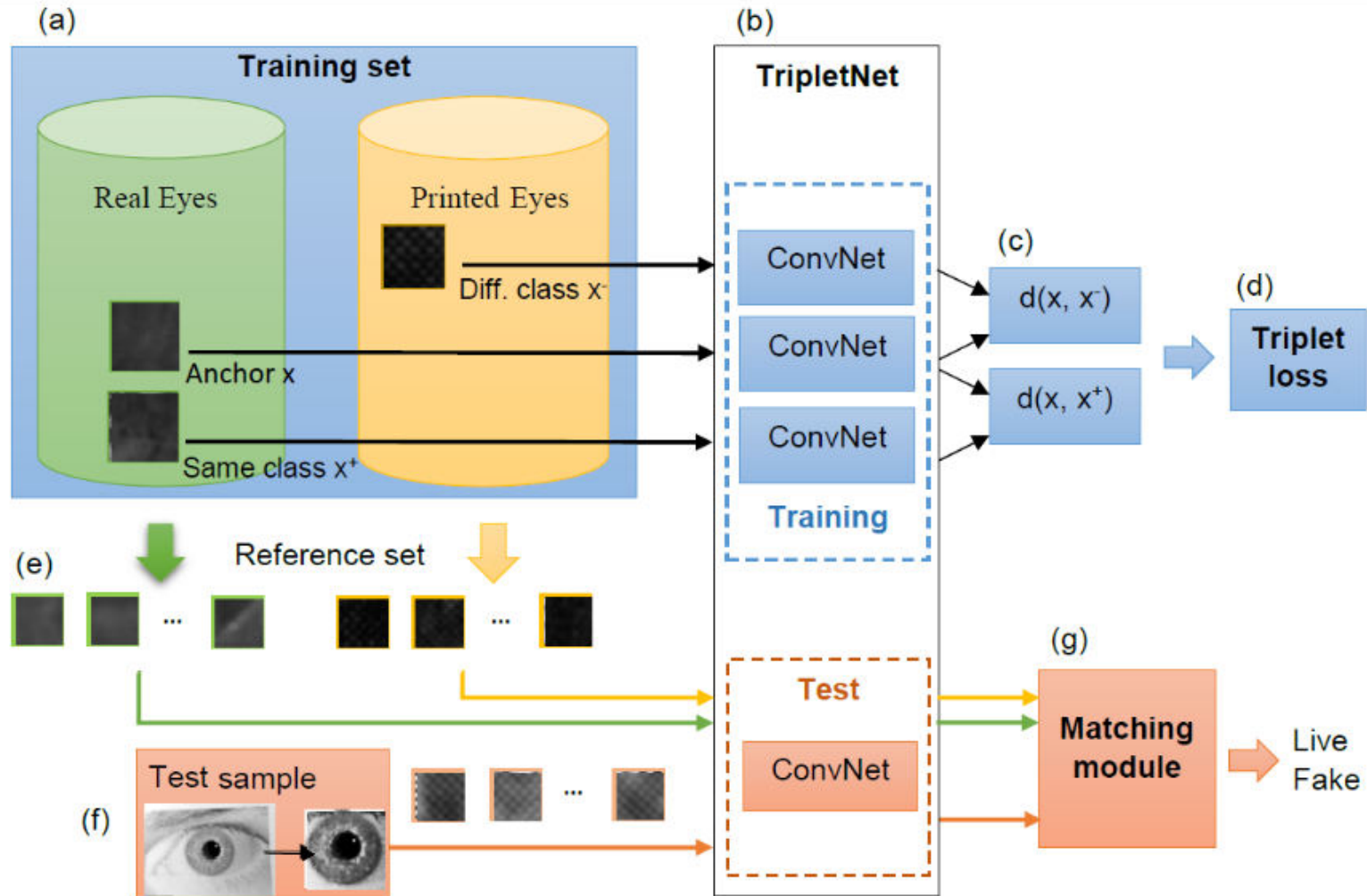


$$c(x_i, x_j^+, x_k^-) = |d(\mathbf{r}(x_i), \mathbf{r}(x_j^+)) - d(\mathbf{r}(x_i), \mathbf{r}(x_k^-)) + 1|_+$$

$$c(x_i, x_j^+) = d(\mathbf{r}(x_i), \mathbf{r}(x_j^+))$$

$$L = \sum_{i,j,k} \left\{ c(x_i, x_j^+, x_k^-) + \beta c(x_i, x_j^+) \right\} + \lambda \|\theta\|_2$$

# Framework



➤ Validation: Classification error leads to **underfitting**

- **Criterion**: how many patches closer to the respective reference set?
- **Stop**: when the number of violating triplets does not decrease for five epochs.

# Results



## › Average Classification Error %

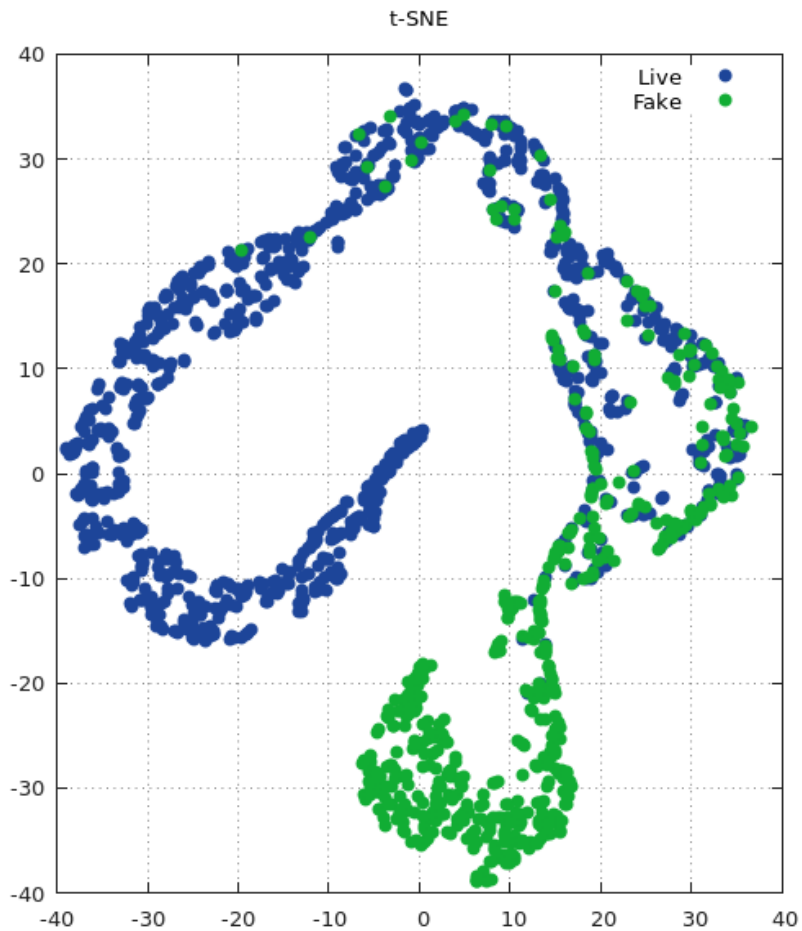
Dataset	Triplet Net	SID	CNN	Dense SIFT	DAISY	LCPD
Iris-2013-Warsaw	0.0	0.0	0.2	0.5	0.9	7.1
Cogent	5.5	6.2	-	13.9	17.2	11.0
Vista	0.7	3.5	-	2.5	8.8	3.1

## › Computational time: 0.2ms + 1ms (GPU)

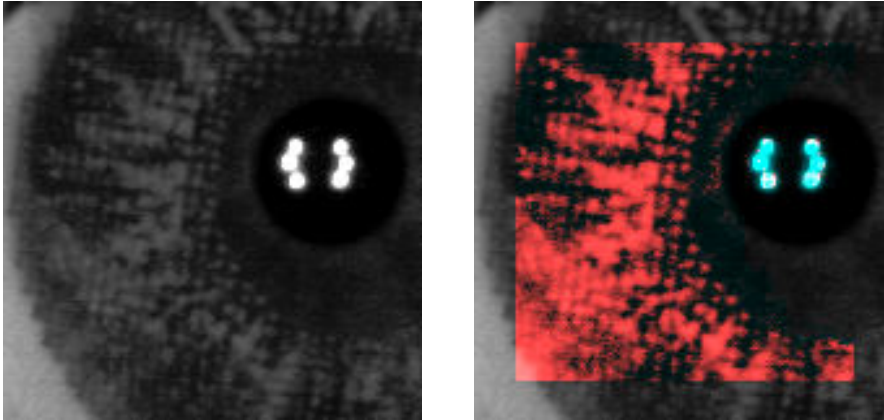
## › Average between

- › Attack Presentation Classification Error Rate (APCER)
- › Bona Fide Presentation Classification Error Rate (BPCER)

# T-SNE Representation

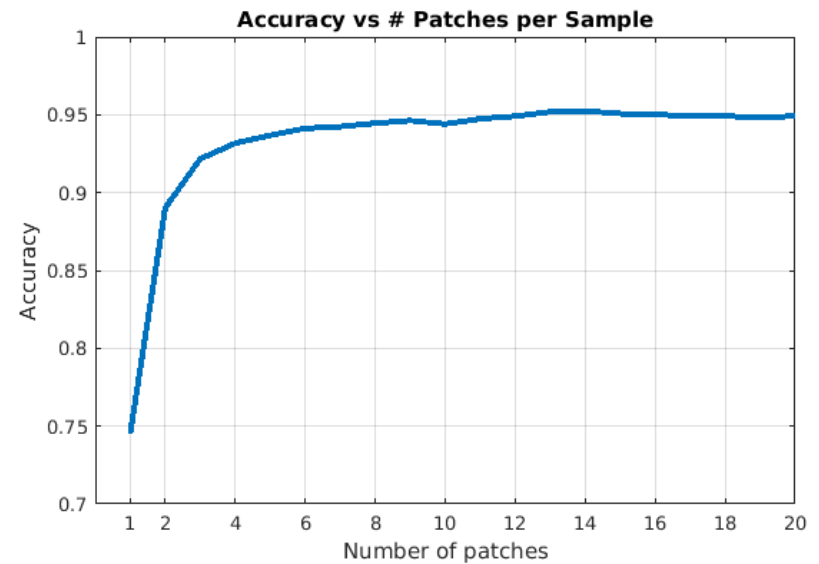


# Visualization



In red, patches classified as Fake (sliding window)

Accuracy wrt the number of patches to evaluate a test iris image



# Conclusions



- › We proposed a **software system** for Iris liveness detection
- › We overcome the **scarcity of examples** by:
  - › **Patch** based representation
    - › Full scale image analysis
  - › Metric learning
    - › Examples arranged in a multitude of **triplets**
- › State of the art or better performance